

Evaluation of a Surface Imaging System's Isocenter Calibration Methods

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Conflicts of Interest

- None

Learning Objectives



To understand the:

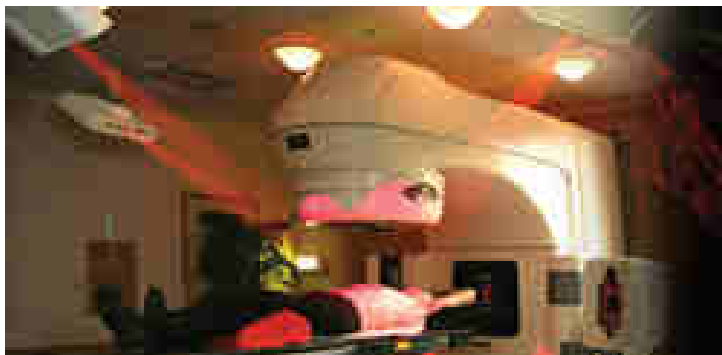
- AlignRT surface imaging technology
- AlignRT clinical uses
 - ▣ With a focus on AlignRT for SRS
- Isocenter calibration methods used by AlignRT
 - ▣ “Monthly Calibration” and “Isocentre Calibration”
- Potential pitfalls of isocenter miscalibration

AlignRT

- Video-based 3D optical surface imaging system from VisionRT
- Utilizes 3 camera pods
 - ▣ 2 lateral, 1 front
- Random speckle pattern projected from each pod
- Visualized by each data camera



(Cervino et al., 2012)

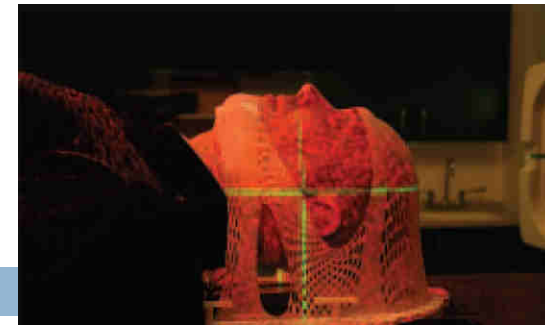


www.visionrt.com

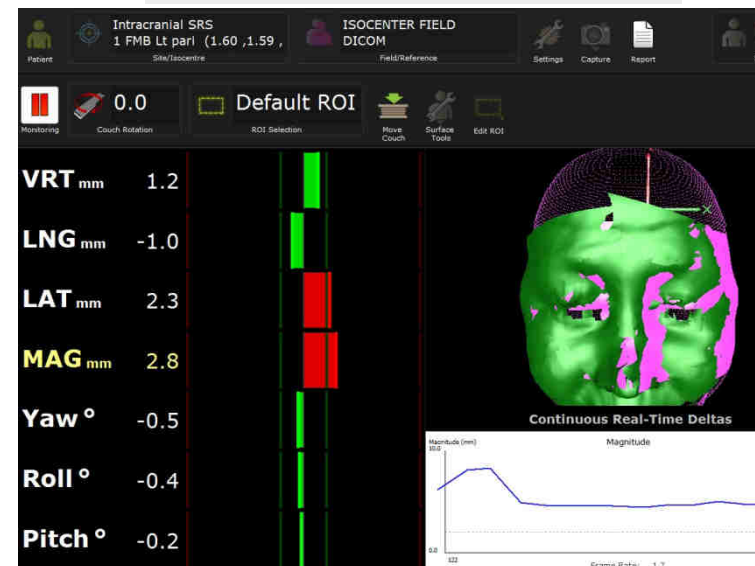
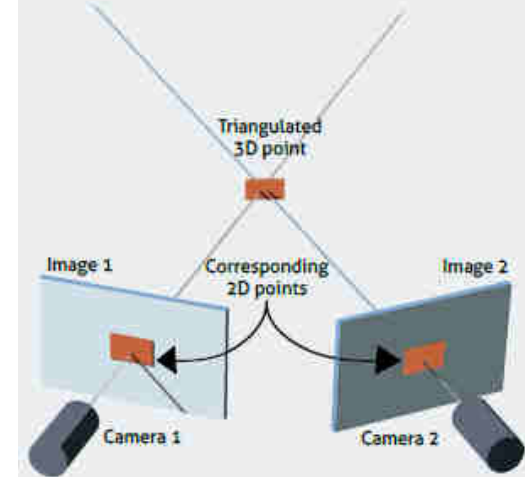


AlignRT

- Speckle pattern provides visual uniqueness to each point of the imaged surface
 - 3D position of a set of points can be determined through triangulation
 - ▣ Camera calibration needed
- AlignRT calculates the displacement needed to align the imaged surface with the reference surface
 - ▣ Translations
 - ▣ Rotations

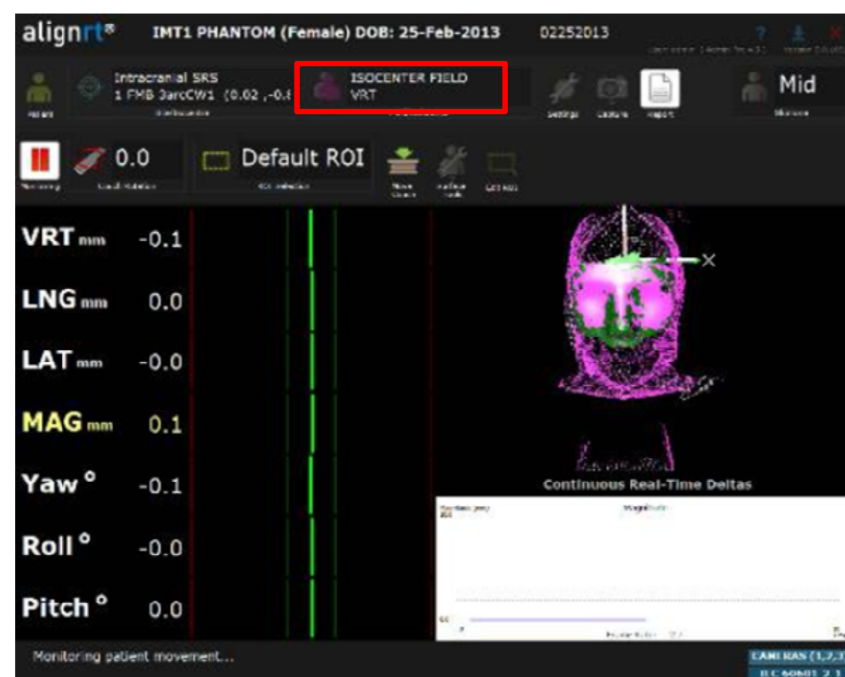
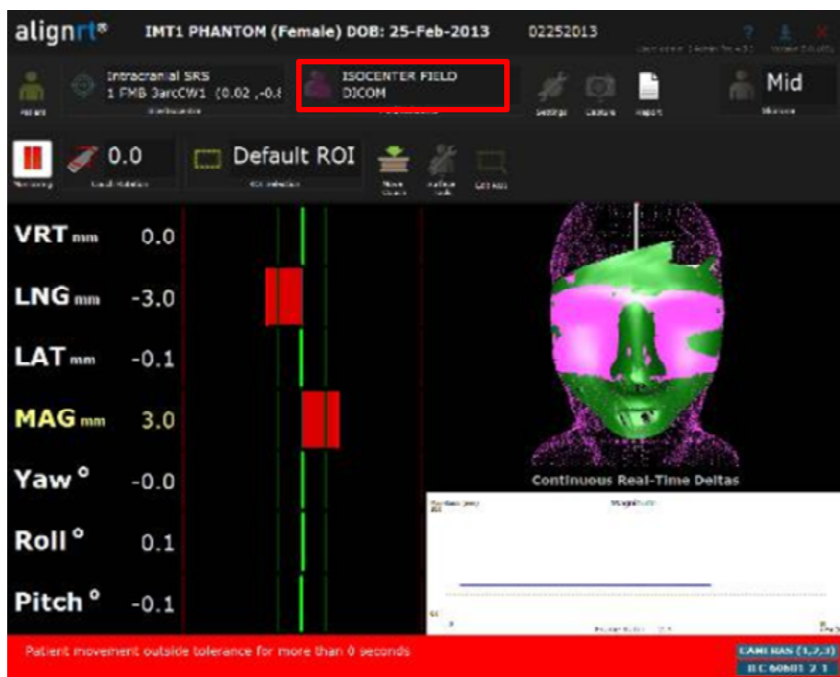


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AlignRT

- Reference surfaces:
 - ▣ Imported body structure from TPS (“DICOM”)
 - ▣ Reference image captured with AlignRT (“VRT”)



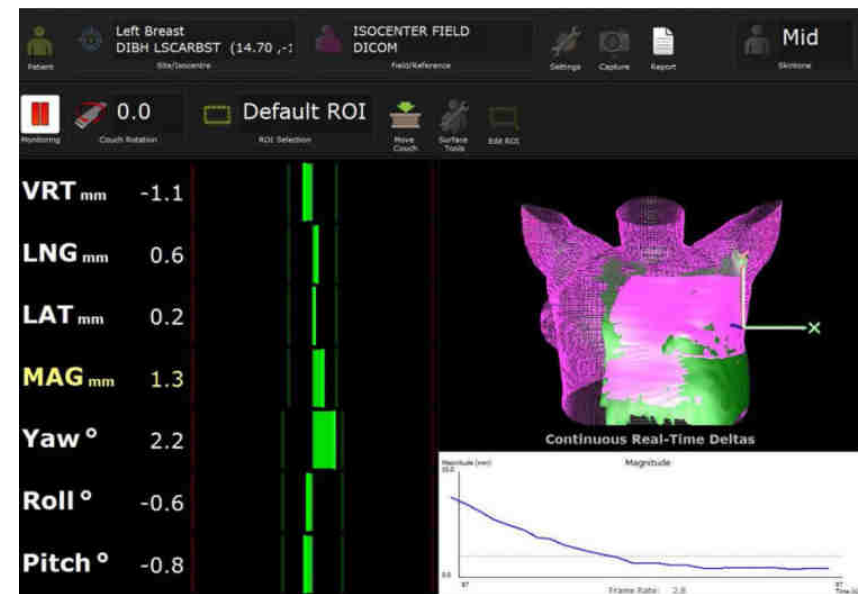
Clinical uses for AlignRT



- Breast
- Extremities
- Head and neck
- Frameless stereotactic radiosurgery (SRS)

Breast

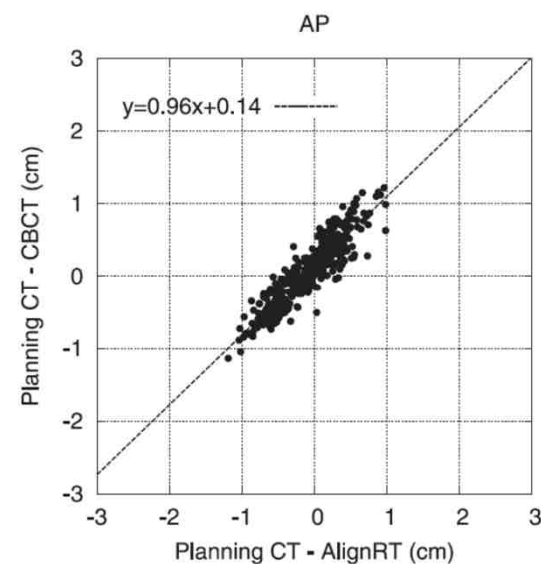
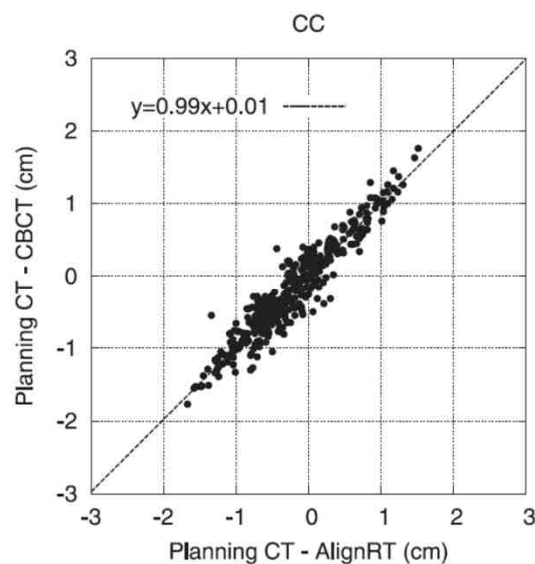
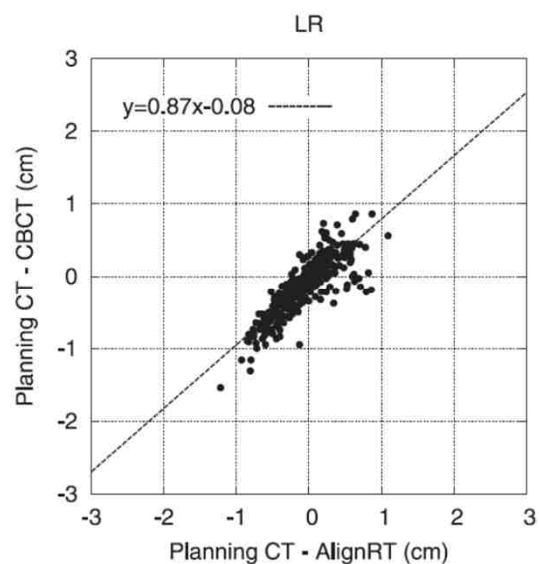
- Deep-inspiration breath-hold (DIBH)
 - To limit dose to the heart for left-sided treatments
- Patient breathes in to reach the same chest-rise as at the time of simulation
- AlignRT allow chest-rise to be evaluated and compared to simulation



(Walston et al., 2016)

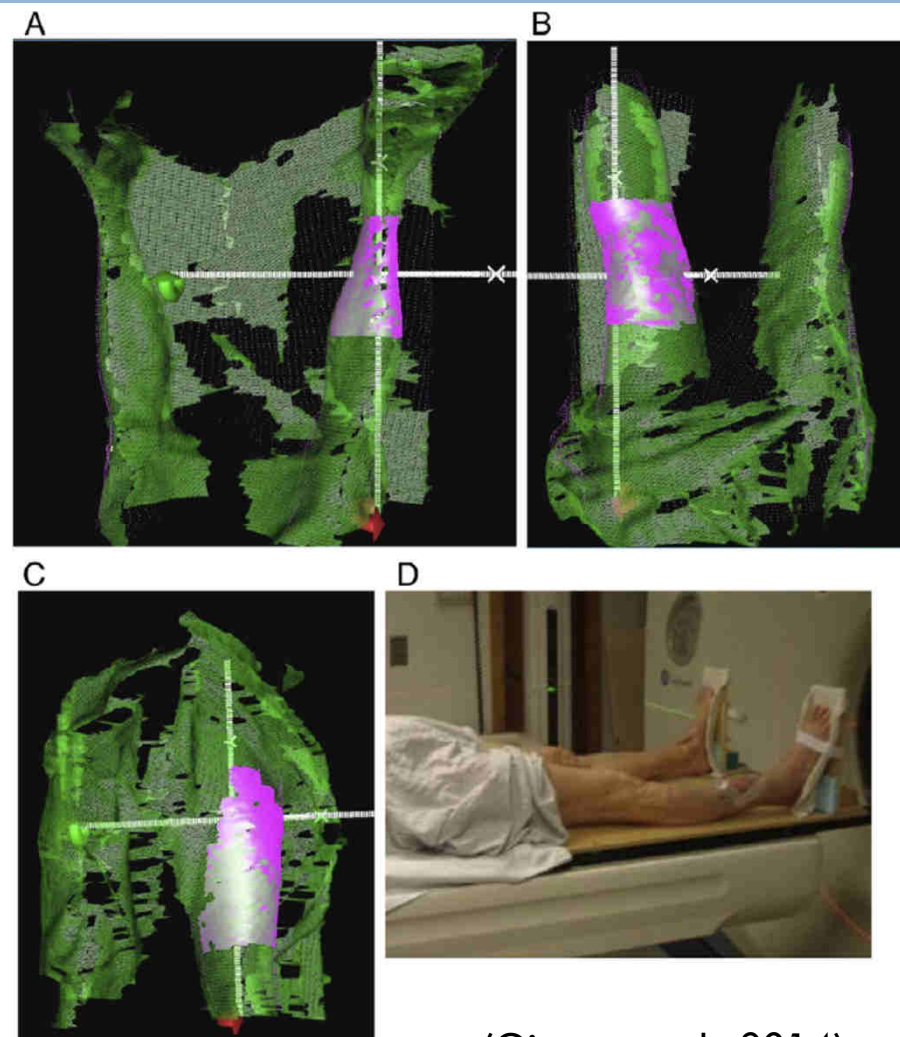
Breast – accurate detection of position

- AlignRT correlates well with CBCT for detecting setup errors during DIBH radiation therapy
- This accuracy supports the use of surface image guidance for this application



Extremities

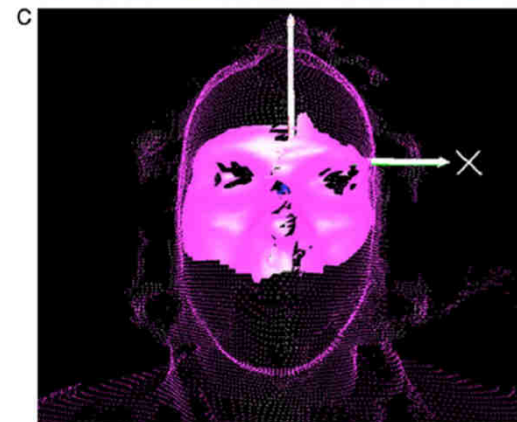
- Proper positioning of patient's with extremity sarcomas can be challenging
 - ▣ Frog leg
 - ▣ Long fields
- Surface imaging can aid in the initial positioning of the patient
 - ▣ Limb rotation prior to radiographic imaging
 - ▣ May prevent the need to repeat imaging



(Gierga et al., 2014)

Head and Neck

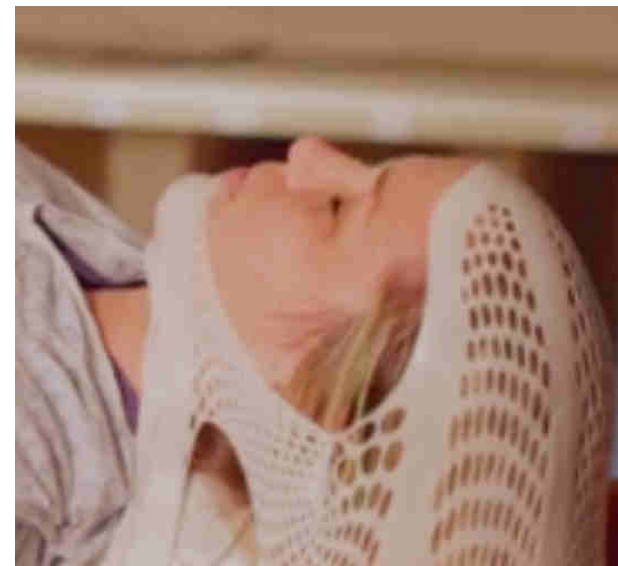
- Helpful for initial patient setup
 - ▣ (Gopan et al., 2012)
- Open face masks allows patient tracking and preserves patient immobilization
 - ▣ (Wiant et al., 2016)
 - ▣ Good for patients with anxiety
- Potential to evaluate neck flexion and shoulder position



(Wiant et al., 2016)

SRS

- System shown to accurately display displacements at the sub mm level
 - ▣ (Li et al., 2011)(Cervino et al., 2010)
- Open face mask to allow system to visualize facial surface for tracking position during treatment



SRS – Clinical outcomes

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Pham et al. Real-time, surface imaging-guided SRS for brain metastases

(2014)

Table 2 Comparison of local control and survival rates in retrospective studies of brain metastases treated with radiosurgery reporting kaplan-meier data^a

Study	Treatment system	Patients, n	Crude LC, %	Actuarial 1-yr LC, %	Actuarial 1-yr OS, %
Schomas <i>et al.</i> (19) [2005]	Frame-based LINAC	80	91	89	33
Bhatnagar <i>et al.</i> (18) [2006]	Frame-based Gamma Knife	205	***	71	37 ^b
Breneman <i>et al.</i> (6) [2009]	Frameless LINAC	53	***	80	44
Nath <i>et al.</i> (7) [2010]	Frameless LINAC	65	88	76	40
Pan <i>et al.</i> (17) [2012]	Frameless, surface-imaging guided LINAC	44	85	76	38
Present series	Frameless, surface-imaging guided LINAC	163	85	79	56

^a, LC indicates local control; LINAC, linear accelerator; ***, not reported; ^b, estimated from Kaplan-Meier curve.

- Frameless, surface-imaging guided linac SRS can achieve outcomes comparable to other frame and frameless SRS techniques

AlignRT for SRS

- Advantages:
 - ▣ Real time tracking
 - ▣ Accurate – sub mm displacements
 - ▣ No biteblock
 - Able to treat patients without teeth
 - ▣ No ionizing radiation
 - ▣ Able to be used with couch rotations
 - ▣ No frame
 - Improved comfort
 - Hypo-fractionated treatments possible
 - No need for re-placement of frame
 - No scheduling needed for frame placement



(Pan et al., 2012)

AlignRT for SRS

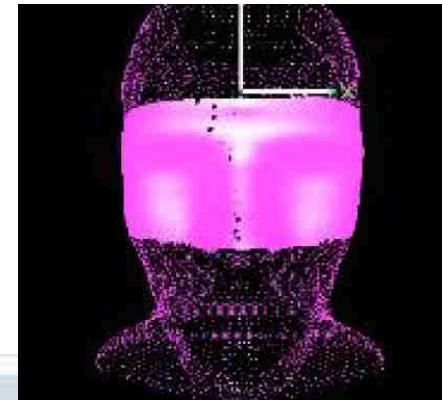
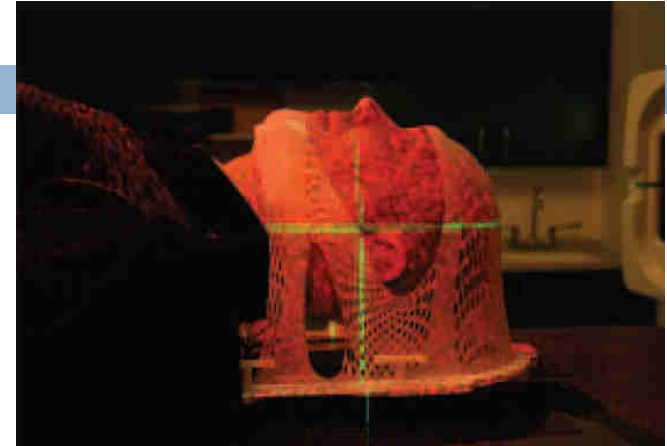


□ Disadvantages

- Using the face as a surrogate for targets within the brain
 - ROI selection important
- Open face masks – not as immobilizing as a full mask or head frame
 - Tradeoff for real-time visualization of position
 - May not work with a non-compliant patient or someone not able to remain still

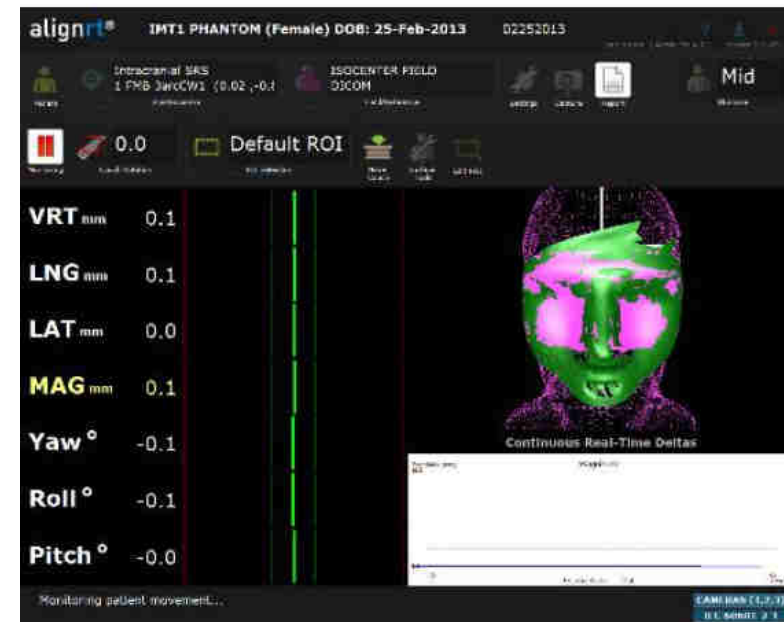
Typical workflow for SRS

- CT sim with open face mask
- Define a ROI on CT-defined reference surface
- Setup head adjustment attachment on couch (if needed)
- Setup patient on the couch
- Apply shifts given to isocenter
 - ▣ Rough positioning
 - ▣ Adjust rotations (to limit additional adjustment)
- Place faceless mask and make shifts indicated by AlignRT until approximately zero
 - ▣ Fine positioning



Typical workflow for SRS

- kV/kV match to check for rotations (e.g., pitch)
- CBCT-indicated shifts are used to put patient in their final Tx position
- New reference image is captured with AlignRT (zero offsets)
- Monitor patient's position during treatment
- Discontinue treatment and reposition if offsets exceed a limit
 - ▣ 1 mm
- Couch angle changed in AlignRT for beams utilizing couch rotations



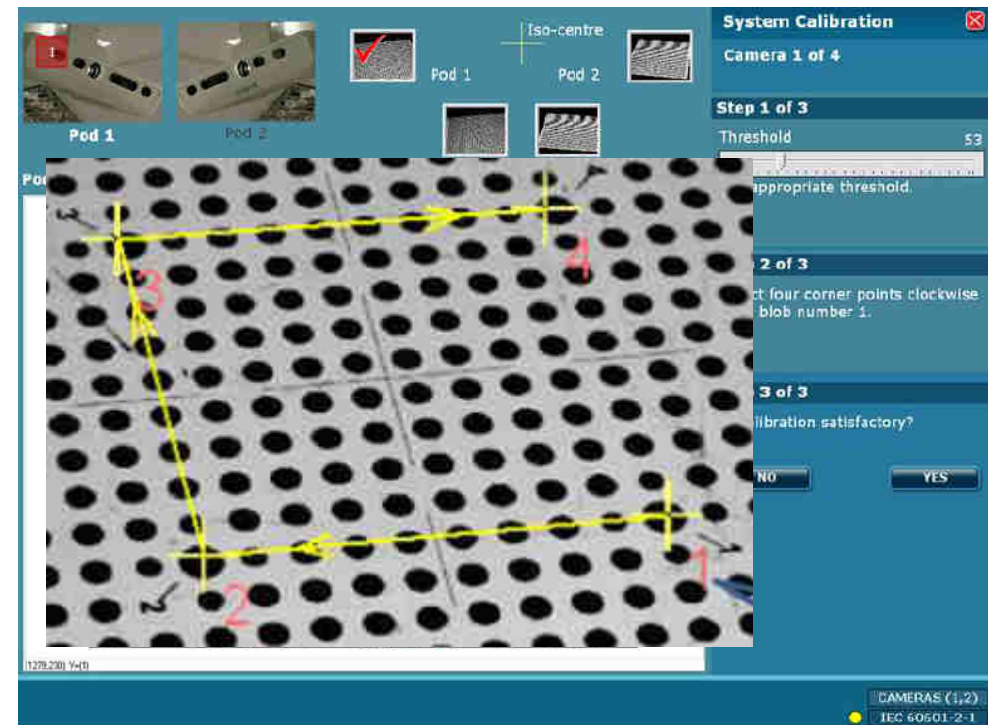
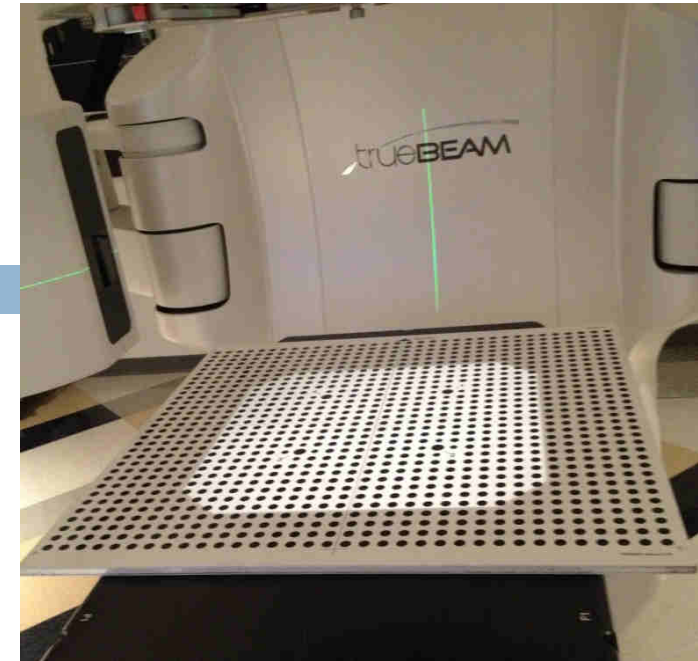
Evaluation of the two isocenter calibration methods

- AlignRT has two methods that can set the imaging system's isocenter
 - “Monthly Calibration”
 - “Isocentre Calibration”

- This work focused on the SRS workflow
 - Tighter tolerances typically required for SRS treatments
 - Couch rotations

Monthly calibration

- Calibration plate placed on couch and aligned with the room lasers or crosshair (100cm SSD)
- An image is captured with each of the cameras (6)
- The orientation of the board is determined with numbered blobs (1-4)
- The other blobs are detected
 - ▣ Known dimension and location
- Spatial correlation between the cameras is established



Monthly calibration

Potential problems:

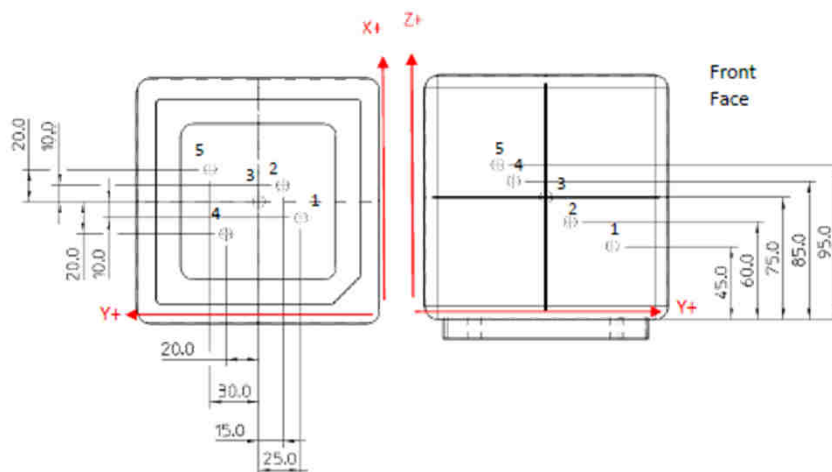
- Aligned to isocenter using surrogates for actual isocenter
 - ▣ ODI, lasers, crosshair, etc.
- Couch may have inherent pitch or roll

- This work evaluates the effects of these potential miscalibrations



Isocentre calibration

- Completed in addition to the monthly calibration
- Utilizes a cube phantom that has five ceramic spheres
 - ▣ One is located in the center of the cube
 - ▣ The other four are arranged asymmetrically around the central sphere

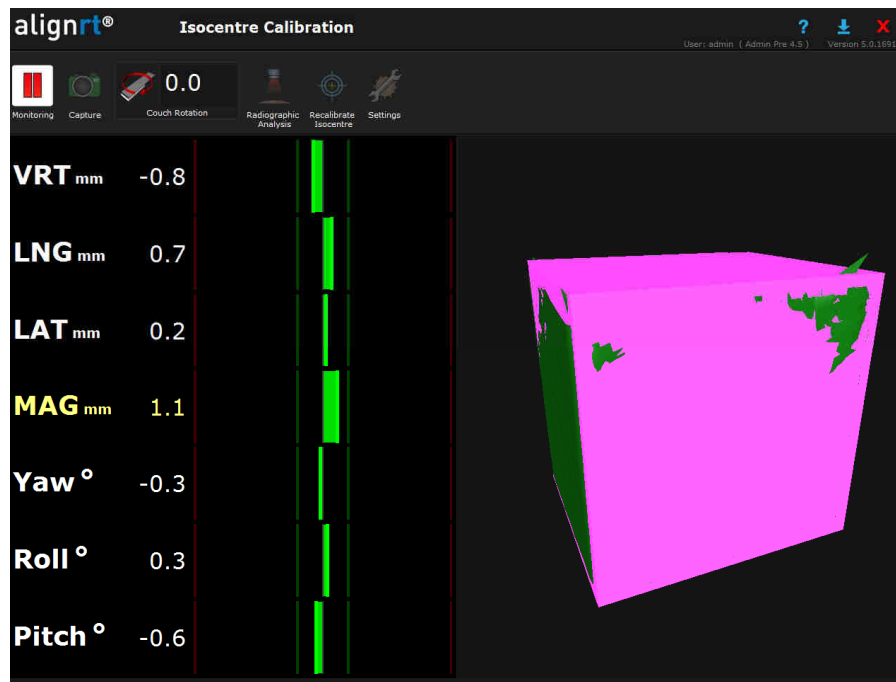


Isocentre calibration

- Position phantom using lasers and field light
- Take 4 MV port images of the cube phantom
 - ▣ AP, PA, L Lat, and R Lat
- Export dicom images to AlignRT
- Enter the isocenter calibration module in AlignRT
- Monitor with the cube phantom in place
 - ▣ Allows AlignRT to see the position of the cube relative to where it calculates it should be based on the board calibration
- Radiographic analysis of the MV images
 - ▣ Determines offsets/rotations of the cube from MV isocenter
- Apply the isocenter calibration
 - ▣ Creates a 4x4 matrix of rotations/shifts of the board calibration to the MV isocenter

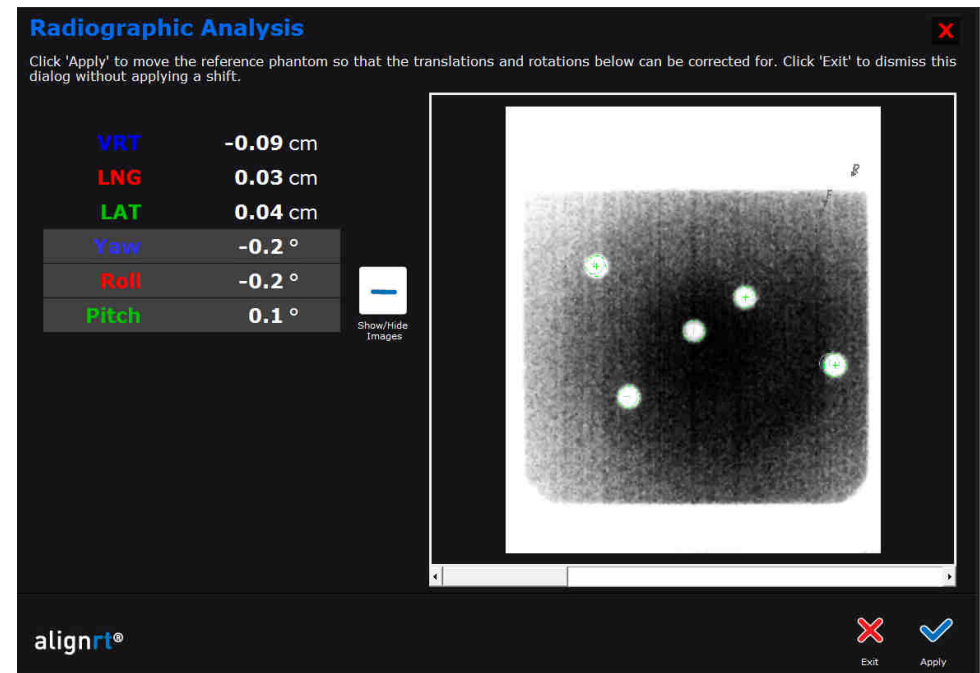
Isocentre calibration

□ Isocenter calibration module screens:



The screenshot shows the 'alignrt® Isocentre Calibration' software interface. The top bar includes the logo, title, and user information (User: admin, Admin Pre 4.5, Version: 5.0.1691). Below the title bar is a navigation menu with icons for Monitoring, Capture, Couch Rotation (0.0), Radiographic Analysis, Recalibrate Isocentre, and Settings. The main display area is divided into three sections: a list of calibration parameters on the left, a vertical strip of green and black bars in the middle, and a 3D visualization of a pink cube with green markers on the right.

Parameter	Value
VRT mm	-0.8
LNG mm	0.7
LAT mm	0.2
MAG mm	1.1
Yaw °	-0.3
Roll °	0.3
Pitch °	-0.6

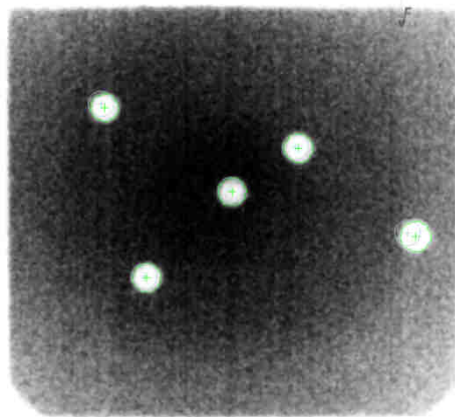


The screenshot shows the 'alignrt® Radiographic Analysis' software interface. The top bar includes the logo, title, and a close button (X). Below the title bar is a text instruction: 'Click 'Apply' to move the reference phantom so that the translations and rotations below can be corrected for. Click 'Exit' to dismiss this dialog without applying a shift.' The main display area is divided into two sections: a list of calibration parameters on the left and a radiographic image on the right. The radiographic image shows a dark square with four bright spots, each marked with a green circle and a crosshair.

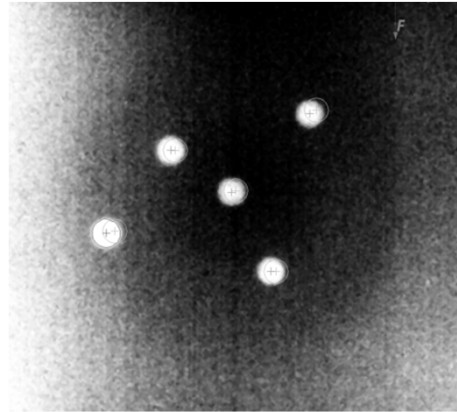
Parameter	Value
VRT	-0.09 cm
LNG	0.03 cm
LAT	0.04 cm
Yaw	-0.2 °
Roll	-0.2 °
Pitch	0.1 °

Isocentre calibration

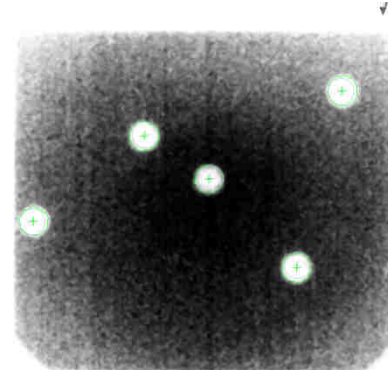
- Radiographic analysis of the portal images
- 4x4 matrix to reposition AlignRT isocenter



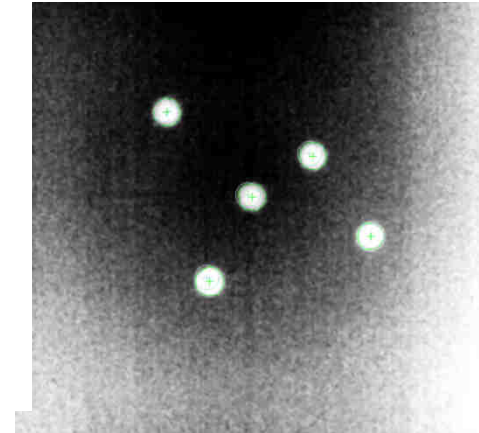
PA



R Lat



AP

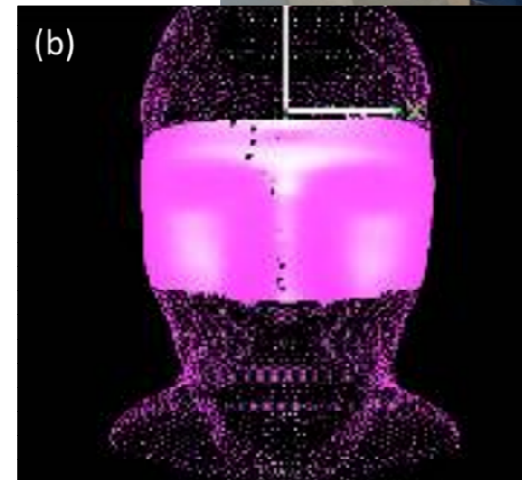
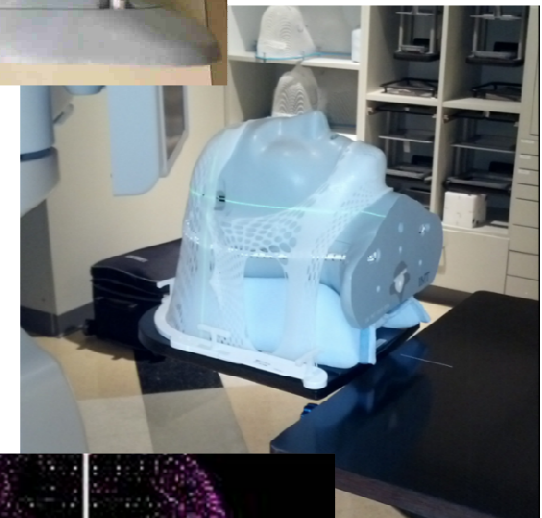


L Lat

0.999997	-0.00175	0.001581	0.226326	Lng
0.001763	0.999987	-0.00486	0.127327	Lat
-0.00157	0.004864	0.999987	-0.11187	Vrt
0	0	0	1	

Head phantom

- MAX-HD anthropomorphic head phantom
- SRS treatment setup was replicated
 - ▣ Open-face mask
- Treatment plan was created with iso roughly centered in the brain
 - ▣ Included fields with couch rotations of 0, 45, 90, 315, and 270°
- Plan and body structure exported to AlignRT
- ROI was defined as open areas of face
- Initially positioned with kV CBCT



Displacements with intentional miscalibrations

- Calibration plate was intentionally shifted away from the linac isocenter in one direction before monthly calibration
 - ± 3 mm in the lng and lat directions
 - ± 1 mm in the lng, lat, and vrt directions
- Head phantom returned to position indicated using CBCT
- Tracking started with CT-defined reference surface
- AlignRT-indicated offsets were recorded at 270 , 315, 0, 45, and 90° couch angles for each intentional calibration misalignment.



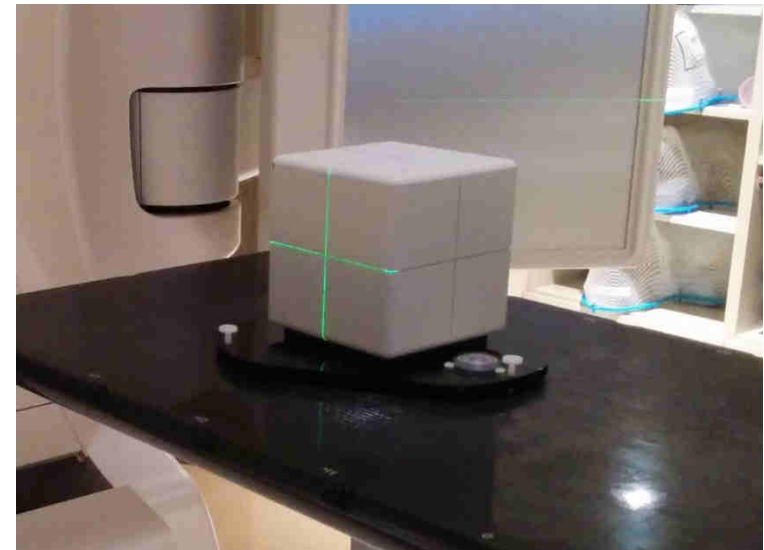
Displacements with intentional miscalibrations

- Repeated for each miscalibration, but with an AlignRT-captured reference surface:
- Head phantom returned to position indicated using CBCT
- A new AlignRT reference surface was captured with the couch at 0°
- AlignRT-indicated offsets were recorded at 270° , 315° , 0° , 45° , and 90° couch angles for each intentional calibration misalignment



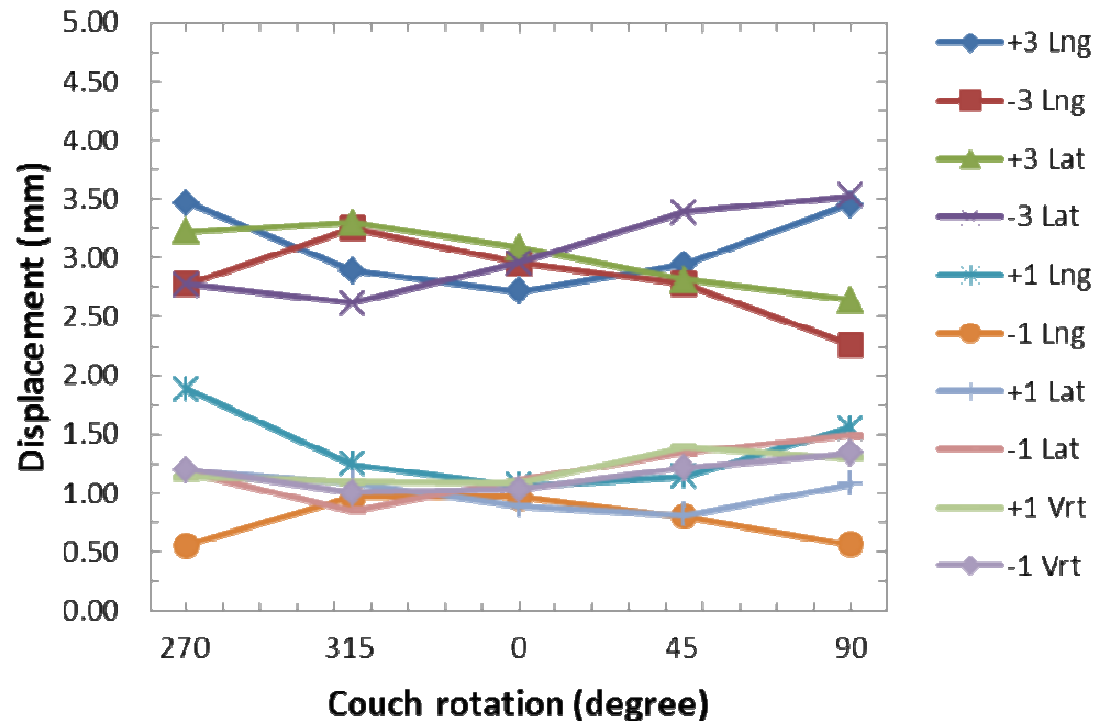
Displacements after isocentre calibration

- Following each miscalibration of the monthly calibration, an isocentre calibration was completed
- An AlignRT-captured reference surface was used (from couch at 0°)
- AlignRT-indicated offsets were recorded at 270 , 315, 0, 45, and 90° couch angles for each intentional calibration misalignment

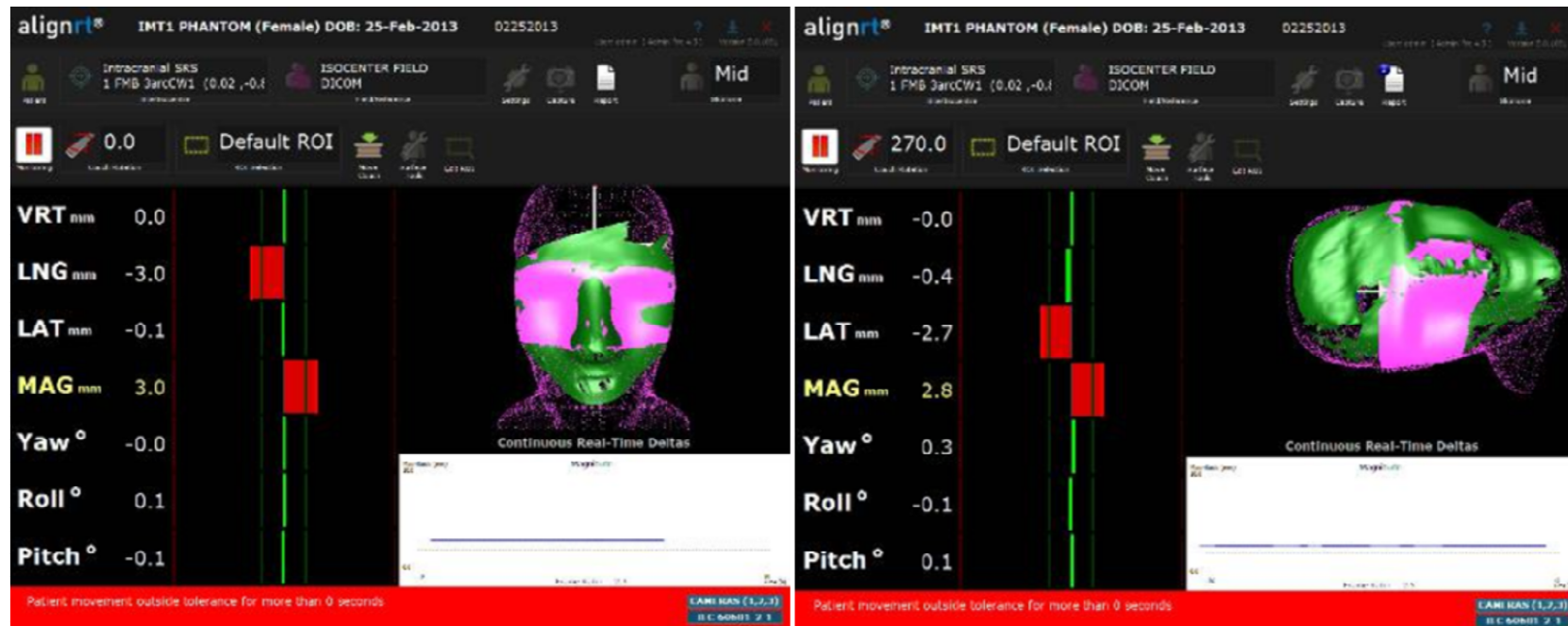


Results: CT-defined ref surface

- Displacement magnitude approximately constant with couch rotation
 - ▣ Plots flat in shape
- Average displacements for 3.0 and 1.0 mm miscalibrations were 3.0 and 1.2 mm, respectively
 - ▣ Approximately equal to the miscalibration magnitude



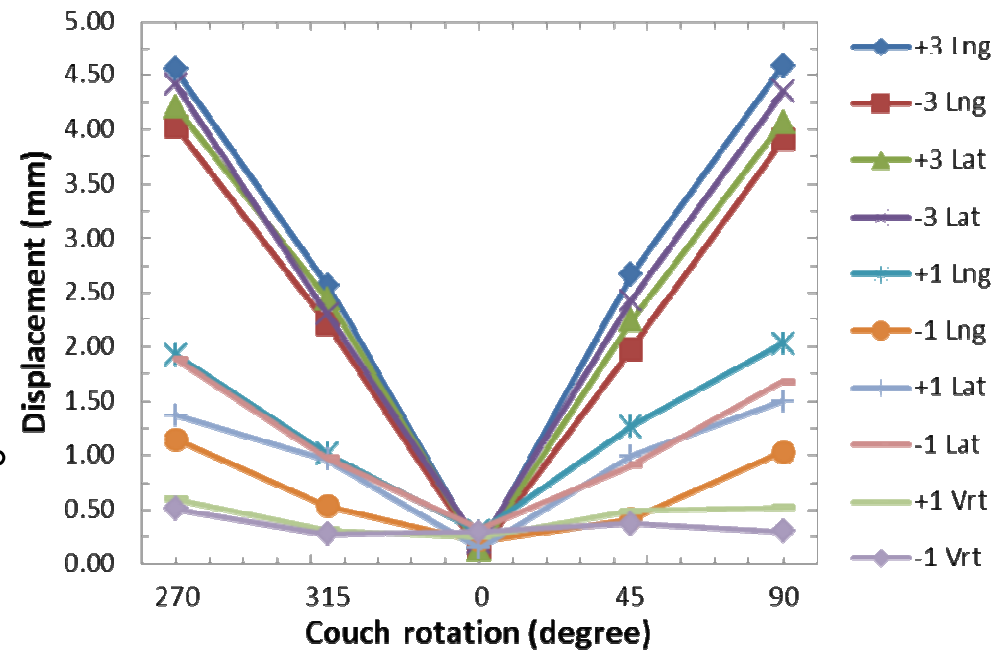
Example: -3mm lng miscalibration



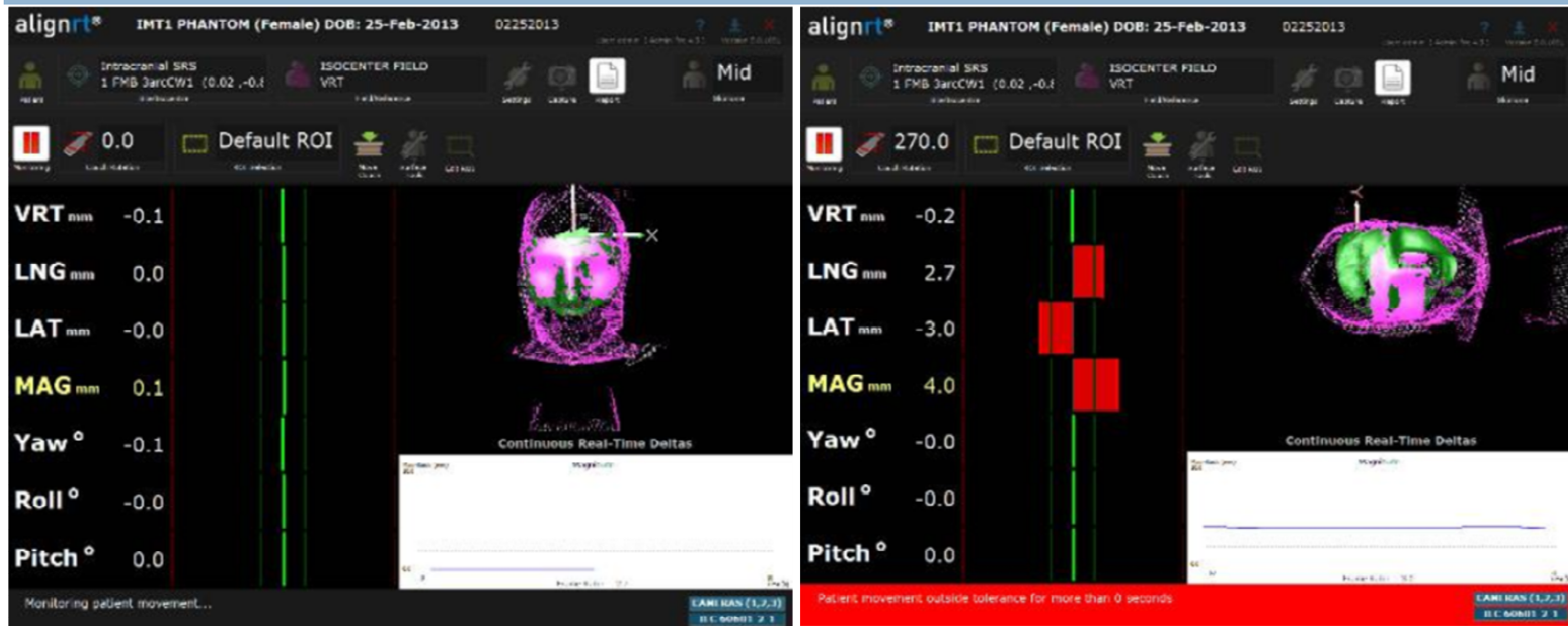
- Rotating from 0 to 270°, the total displacement remains constant
- The direction of the displacement changes from lng to lat – staying the same relative to the room

Results: AlignRT-captured ref surface

- Displacement magnitude increases with couch rotations for lng and lat miscalibrations
 - Faster increase for larger miscalibrations
- Average displacement at 0° was 0.2mm
- Average displacement at $\pm 90^\circ$ was 4.3 and 1.6mm for 3.0mm and 1.0mm miscalibrations
- For vrt miscalibrations, the largest indicated displacement was 0.6 mm



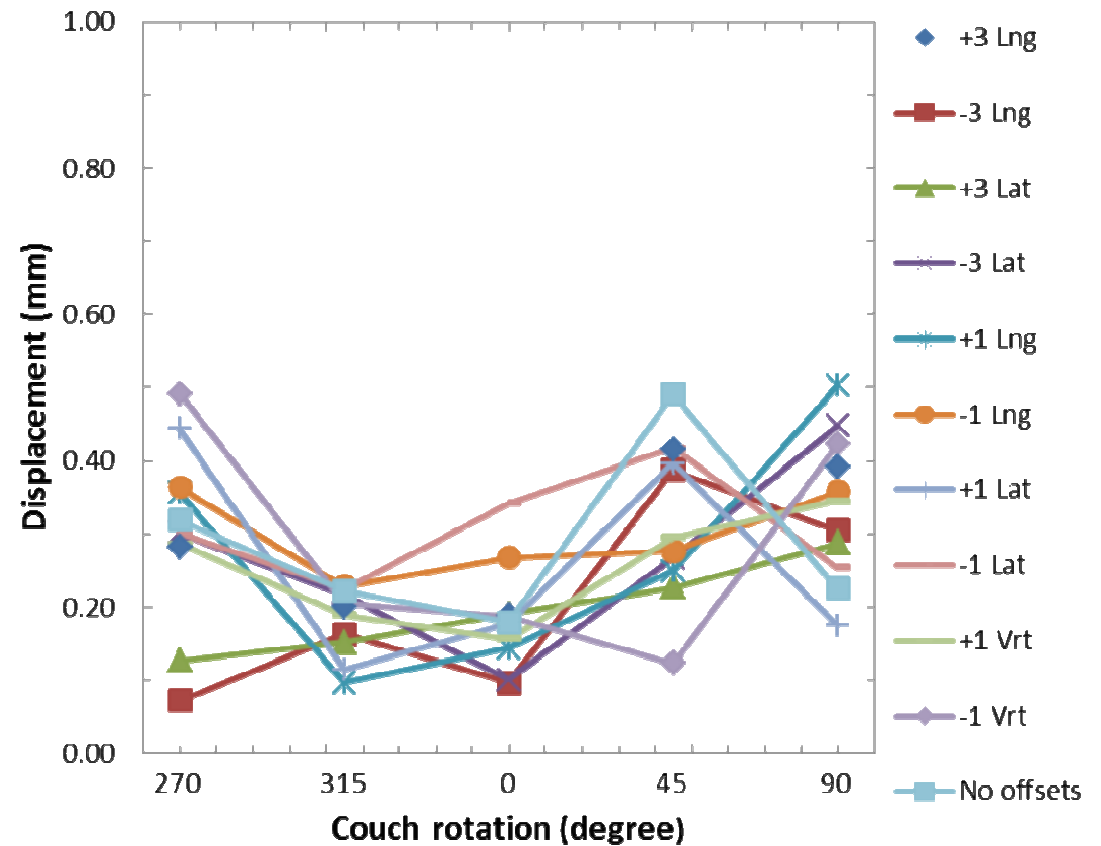
Example: -3mm lng miscalibration



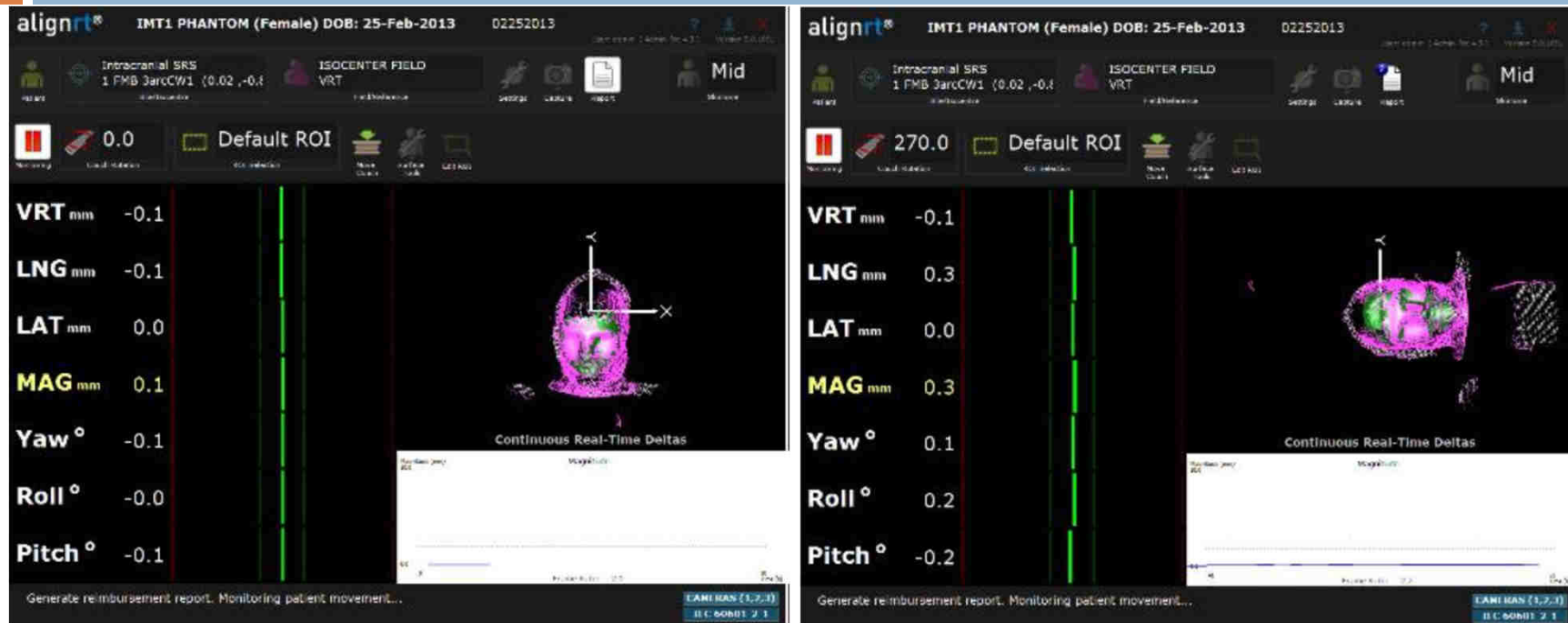
- Rotating from 0 to 270°, the total displacement increased from 0.1 mm to 4.0 mm
- Offsets in both the lng and lat directions

Results: after isocentre calibration

- With an AlignRT-captured ref surface
- Displacements ranged from 0.1 to 0.5mm for all couch rotations
- These values are within the expected range of walkout observed for this couch from ongoing QA tests



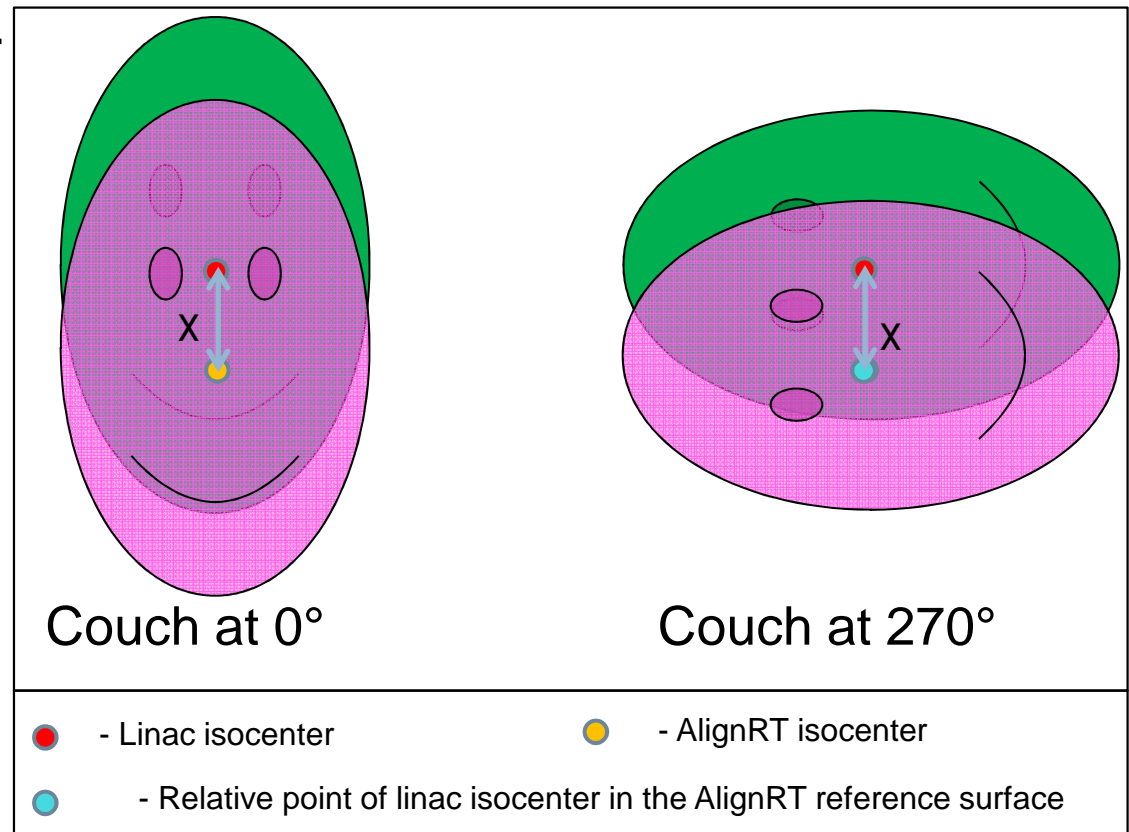
Example: after isocentre calibration



- Rotating from 0 to 270°, the total displacement increased from 0.1 mm to 0.3 mm

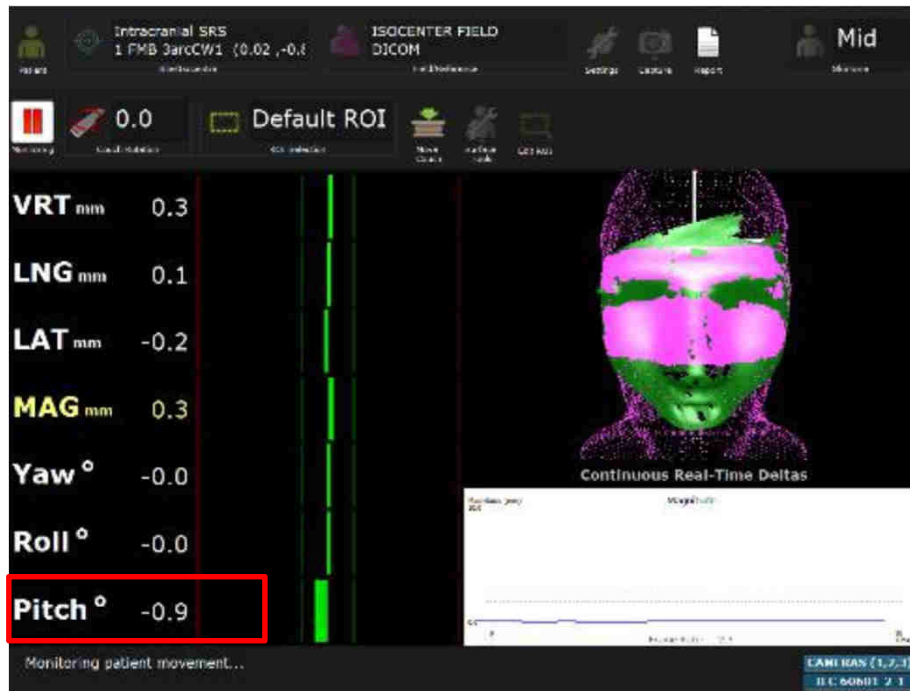
Discussion: CT-defined ref surface

- Miscalibrations result in systematic offsets in the reference surface
- Relevant for when AlignRT is used for initial patient setup or DIBH
 - DIBH
 - Extremities
 - H&N
- Careful placement of the calibration plate is needed to limit these effects



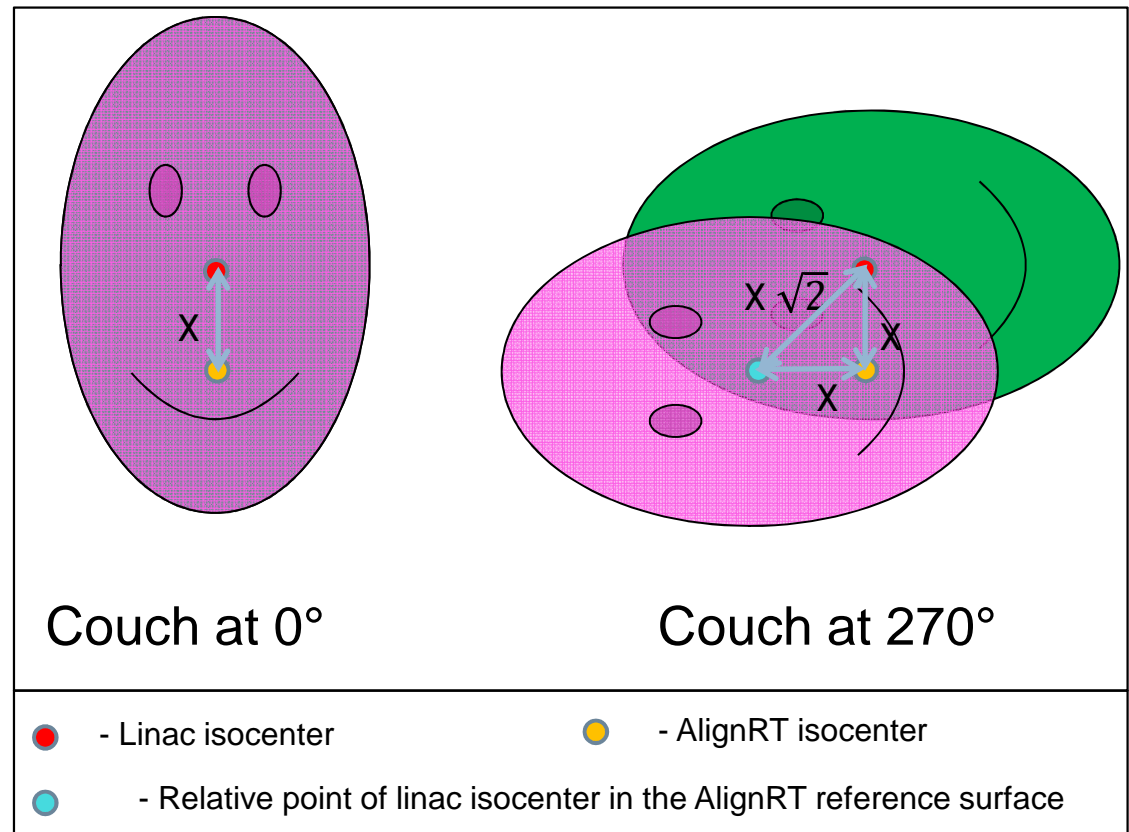
Discussion: CT-defined ref surface

- Intentionally miscalibrated with the calibration board pitched 1°
- Rotational miscalibrations also propagate



Discussion: AlignRT-captured ref surface

- Based on geometry alone, the displacements should be equal to $X \sqrt{2}$ for lng and lat miscalibrations
- This would be 4.2 and 1.4mm for 3.0 and 1.0mm miscalibrations, respectively
- The average were 4.3 and 1.6mm
 - ▣ Include some couch walkout



Discussion: AlignRT-captured ref surface



- For Vrt shifts:
 - ▣ Calibration offsets were along axis of rotation
 - ▣ Offsets are independent of couch rotation
 - ▣ All displacements within 0.6mm for all couch angles
- Isocentre calibration resolves the miscalibration artifacts observed with couch rotations

Isocentre calibration

- Based on geometry, a $\sqrt{2}/2$ (0.7mm) miscalibration would result in a 1.0mm displacement at 90° couch rotations
- 4x4 matrix to reposition AlignRT isocenter... from before

~ 0.3 mm displacement

0.999997	-0.00175	0.001581	0.226326	Lng
0.001763	0.999987	-0.00486	0.127327	Lat
-0.00157	0.004864	0.999987	-0.11187	Vrt
0	0	0	1	

0mm offsets

0.999996	-0.0029	3.73E-05	0.346394	Lng
0.002902	0.999986	-0.00448	2.95379	Lat
-2.43E-05	0.00448	0.99999	-0.11833	Vrt
0	0	0	1	

+3mm Lat offset

- Positioning the calibration board within 0.7 mm of isocenter could be challenging

Conclusions



- The potential pitfalls of the monthly calibration method have been demonstrated
- The advantages of the isocentre calibration method have been established.
 - ▣ Effectively removes the potential miscalibration artifacts of the monthly calibration
 - ▣ Especially critical for methods that require tight tolerances and utilize couch rotations
 - ▣ Less critical for treatments that do not have these requirements – provided the monthly calibration was performed carefully

Acknowledgements



- Co-authors: Ryan Manger, Todd Pawlicki, and Grace Kim
 - Paxton AB, Manger RP, Pawlicki T, Kim G. Evaluation of a surface imaging system's isocenter calibration methods. J Appl Clin Med Phys. 2017;18:85-91.
- Ed Mead from VisionRT
- Umar Baharom from IMT

- Thank you for your attention

Questions?



References

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